

EFSM Semantics*

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1 Syntax

Definition 1.1 An EFSM (extended finite state machine) \( E \) is a tuple \( \langle N, n_0, T, V \rangle \), where

- \( N \) is a set of nodes,
- \( n_0 \) is the initial node,
- \( T \) is a set of transitions, and
- \( V = V_g \cup V_l \) is a set of typed variables.

All sets are assumed to be finite. \( \square \)

Each node \( n \in M \) represents a unique place and can have a label to identify it.

A transition \( t \in T \) is of the form \( \langle n, g, \alpha, n' \rangle \), where \( n \) is the source node, \( g \) is the guard condition over variables, \( \alpha \) is the action that represents a set of assignments over variables, and \( n' \) is the target node.

The set \( V \) of variables are partitioned into two disjoint subsets, \( V_g \) and \( V_l \). The set \( V_g \) is called global variables and the set \( V_l \) is called local variables. For a given EFSM, its global variables are visible outside the EFSM, and local variables are not visible outside the EFSM but can be used within the EFSM. Each variable \( x \) has a value domain, \( \text{dom}(x) \), and global variables, \( V_g \) may have a set of possible initial values.

1.1 Operations on EFSMs

There are various operations on EFSMs to allow the construction of an EFSM from its component EFSMs.

Variable Hiding. The hiding operator makes a set of EFSM variables local.

Definition 1.2 Given an EFSM \( E = \langle N, n_0, T, V_g \cup V_l \rangle \), the EFSM \( E_{\text{h}} = \langle N, n_0, T, V_g' \cup V_l' \rangle \), where \( V_g' = V_g - V_h \) and \( V_l' = V_l \cup V_h \).

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**Parallel Composition.** The parallel composition of EFSMs allows the construction of a complex EFSM from simpler EFSMs.

**Definition 1.3** Given two EFSMs, $E_1$ and $E_2$, the parallel composition $E_1 \parallel E_2$ is an EFSM $E = \langle N, n_0, T, V_g \cup V_i \rangle$, where

- $N = E_1.S \times E_2.S$,
- $n_0 = (E_1.n_0, E_2.n_0)$,
- $T$ is given as follows (note that this is pure interleaving): for $\langle n_1, g_1, \alpha_1, n'_1 \rangle \in E_1.T$ and $\langle n_2, g_2, \alpha_2, n'_2 \rangle \in E_2.T$, $T$ includes $\langle (n_1, n_2), g_1, \alpha_1, (n'_1, n_2) \rangle$ and $\langle (n_1, n_2), g_2, \alpha_2, (n_1, n'_2) \rangle$. (Note: We could also include $\langle (n_1, n_2), g_1 \land g_2, \alpha_1 \cup \alpha_2, (n'_1, n'_2) \rangle$.)
- $V_g = E_1.V_g \cup E_2.V_g$, and $V_i = (E_1.V_i \cup E_2.V_i)$. (Note that we assume that $E_1.V_i \cap E_2.V_i =$.)

□

Restriction: Each variable in $V_g$ is either read only or read/write. If a global variable is declared as read/write in one (primitive) EFSM, it cannot be declared as read/write in another EMFS.

Other operators to consider later:

- Parallel operators used in PET
- Sequential composition, abort/kill a subprocess

## 2 Semantics

Given a set of variables in $V$, we use $Q_v$ to denote a valuation of the variables in $V$. The value of a variable $x$ in the valuation $Q$ is denoted as $Q(x)$.

In modeling the execution of an EFSM, a state is represented by a pair $\langle n, Q \rangle$, where $n$ is a node, $Q = Q_g \cup Q_i$ is the valuation of the variables $V = V_g \cup V_i$. The execution of an EFSM starts at a state $\langle n_0, Q_0 \rangle$, where $n_0$ is the initial node and $Q_0$ is the valuation that is consistent with the constraints, $Init(V_g)$, for the initial values of $V_g$. (Note: Should this constraints be part of the EFSM definition?)

A transition $\langle n, g, \alpha, n' \rangle$ can be taken from the current state $\langle n, Q \rangle$ only if the current valuation satisfies the guard condition $g$. The effect of taking the transition $\langle n, g, \alpha, n' \rangle$ from a state $\langle n, Q \rangle$ is a state $\langle n', Q' \rangle$, where $Q'$ is the new valuation resulted from executing the assignment statements specified in the set $\alpha$.

**Definition 2.1** An execution of an EFSM $E = \langle N, n_0, T, V \rangle$ is a finite or infinite sequence of the form

$s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \ldots$

where $s_i = \langle n_i, Q_i \rangle$ satisfying

1. Initially:
2. Succession Constraint:

(Need to define compositionally, that is, allow enviromental update on $V_g$.)

3. Tools

For concrete syntax and tool support, we should use either CHARON or SPIN.